

# Characterization of Lipschitz continuous DC functions\*

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## Abstract

We give a necessary and sufficient condition for a difference of convex (DC, for short) functions, defined on a locally convex space, to be Lipschitz continuous. Our criterion relies on the intersections of the  $\varepsilon$ -subdifferentials of the involved functions.

**Key words.** DC functions, Lipschitz continuity, Integration formulas,  $\varepsilon$ -subdifferential

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## 1 Introduction

In this paper, we work with a (Hausdorff) real locally convex topological vector space  $X$  whose dual is denoted by  $X^*$ . The duality product is denoted by  $\langle \cdot, \cdot \rangle : X \times X^* \rightarrow \mathbb{R}$ , and the zero vector (in  $X$  and  $X^*$ ) by  $\theta$ .

Classical integration formulas ([8, 9]) have been first established in the Banach spaces setting for proper lower semicontinuous (lsc, for short) convex functions using the Fenchel subdifferential, which is defined for a given function  $f : X \rightarrow \mathbb{R} \cup \{+\infty\}$  and a point  $x$  in the domain of  $f$ ,  $\text{dom } f := \{x \in X \mid f(x) < +\infty\}$ , by

$$\partial f(x) := \{x^* \in X^* : f(y) - f(x) \geq \langle y - x, x^* \rangle \text{ for all } y \in X\}.$$

These results have been extended outside the Banach space ([1, 7]) and the non-convex settings ([3]) by using the  $\varepsilon$ -subdifferential mapping, defined for  $\varepsilon > 0$

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by

$$\partial_\varepsilon f(x) := \{x^* \in X^* \mid f(y) - f(x) \geq \langle y - x, x^* \rangle - \varepsilon \text{ for all } y \in X\}.$$

In this paper we exploit an idea, recently used in [6], to establish several characterizations for the Lipschitz character of the difference of convex (DC, for short) functions. As a consequence, if the Lipschitz constant is equal to 0 then we obtain an integration formula guaranteeing the coincidence of the involved functions up to an additive constant. The main result is presented in Theorem 1 in a slightly more general form, valid in the locally convex spaces setting, which characterizes the domination of the variations of DC functions by means of a convex continuous functions. The desired integration formula is obtained in Theorem 5.

## 2 The main result

The desired results providing the characterization of Lipschitz DC functions will be given in Theorem 5, which is a consequence of the following theorem.

In what follows,  $f, g : X \longrightarrow \mathbb{R} \cup \{+\infty\}$  are two given functions with a common domain

$$D := f^{-1}(\mathbb{R}) = g^{-1}(\mathbb{R}),$$

assumed nonempty and convex.

**Theorem 1** *Let  $h : X \longrightarrow \mathbb{R}$  be a continuous convex function such that  $h(\theta) = 0$ . Then, the following statements are equivalent:*

(i)  *$f$  and  $g$  are convex, lsc on  $D$ , and satisfy*

$$f(x) - g(x) \leq f(y) - g(y) + h(x - y) \text{ for all } x, y \in D.$$

(ii) *For each  $x \in D$*

$$\emptyset \neq \partial_\varepsilon f(x) \subset \partial_\varepsilon g(x) + \partial_\varepsilon h(\theta) \text{ for all } \varepsilon > 0.$$

(iii) *For each  $x \in D$  there exists  $\delta > 0$  such that*

$$\emptyset \neq \partial_\varepsilon f(x) \subset \partial_\varepsilon g(x) + \partial_\varepsilon h(\theta) \text{ for all } \varepsilon \in (0, \delta).$$

(iv) *For each  $x \in D$*

$$\partial_\varepsilon f(x) \cap (\partial_\varepsilon g(x) + \partial_\varepsilon h(\theta)) \neq \emptyset \text{ for all } \varepsilon > 0.$$

(v) *For each  $x \in D$  there exists  $\delta > 0$  such that*

$$\partial_\varepsilon f(x) \cap (\partial_\varepsilon g(x) + \partial_\varepsilon h(\theta)) \neq \emptyset \text{ for all } \varepsilon \in (0, \delta).$$

**Proof.** (i)  $\implies$  (ii). Since  $f$  is proper ( $\text{dom } f \neq \emptyset$ ), convex and lsc on  $D$ , for any given  $\varepsilon > 0$  the  $\varepsilon$ -subdifferential operator  $\partial_\varepsilon f$  is nonempty on  $D$  ([11, Prop. 2.4.4(iii)]). For  $x \in D$ , we define the function  $\tilde{g} : X \rightarrow \mathbb{R} \cup \{+\infty\}$  as

$$\tilde{g} := g + f(x) - g(x)$$

so that by (i) the inequality  $f \leq \tilde{g} + h(\cdot - x)$  holds, as well as  $f(x) = \tilde{g}(x) + h(\theta) = \tilde{g}(x)$ . Notice that  $\text{cl } \tilde{g} = \text{cl } g + f(x) - g(x)$ , where  $\text{cl}$  refers to the corresponding lsc envelope. Hence, as  $g$  is lsc on  $D$ ,  $\text{cl } \tilde{g}$  coincides with  $g + f(x) - g(x)$  on  $D$ , which implies that it is proper. Therefore, since ([4, Lemma 15])

$$\text{cl}(\tilde{g} + h(\cdot - x)) = \text{cl } \tilde{g} + h(\cdot - x) = \text{cl } g + h(\cdot - x) + f(x) - g(x)$$

and  $\partial_\delta(\text{cl } \tilde{g})(x) = \partial_\delta \tilde{g}(x) = \partial_\delta g(x)$  (for all  $\delta > 0$ ), by appealing to the sum rule of the  $\varepsilon$ -subdifferential (e.g., [11, Theorem 2.8.3]) we get

$$\begin{aligned} \partial_\varepsilon f(x) &\subset \bigcup_{\substack{\varepsilon_1, \varepsilon_2 \geq 0 \\ \varepsilon_1 + \varepsilon_2 = \varepsilon}} (\partial_{\varepsilon_1}(\text{cl } \tilde{g})(x) + \partial_{\varepsilon_2} h(\theta)) \\ &= \bigcup_{\substack{\varepsilon_1, \varepsilon_2 \geq 0 \\ \varepsilon_1 + \varepsilon_2 = \varepsilon}} (\partial_{\varepsilon_1} g(x) + \partial_{\varepsilon_2} h(\theta)) \subset \partial_\varepsilon g(x) + \partial_\varepsilon h(\theta); \end{aligned}$$

showing that (ii) holds.

The implication (ii)  $\implies$  (iii)  $\implies$  (v) and (ii)  $\implies$  (iv)  $\implies$  (v) are obvious.

(v)  $\implies$  (i). We fix  $x, y \in D$  and take an arbitrary number  $\varepsilon > 0$ . For  $m = 1, 2, \dots$  we denote

$$x_{m,i} := x + \frac{i}{m}(y - x) \quad \text{for } i = 0, 1, \dots, m.$$

Then, by the current assumption (v) for each  $i$  and  $m$  there exists  $\gamma_{m,i} \in (0, m^{-1})$  such that

$$\partial_{m^{-1}\gamma_\varepsilon} f(x_{m,i}) \cap [\partial_{m^{-1}\gamma_\varepsilon} g(x_{m,i}) + \partial_{m^{-1}\gamma_\varepsilon} h(\theta)] \neq \emptyset \quad \text{for all } \gamma \in (0, \gamma_{m,i}).$$

Set

$$\gamma_m := \min_{i \in \{1, \dots, m\}} \gamma_{m,i},$$

so that  $\gamma_m > 0$ , and choose  $u_{m,i}^* \in \partial_{m^{-1}\gamma_m \varepsilon} f(x_{m,i})$ ,  $v_{m,i}^* \in \partial_{m^{-1}\gamma_m \varepsilon} g(x_{m,i})$  and  $w_{m,i}^* \in \partial_{m^{-1}\gamma_m \varepsilon} h(\theta)$  such that  $u_{m,i}^* = v_{m,i}^* + w_{m,i}^*$  for  $i = 1, \dots, m-1$ . In this way, if  $u^* \in \partial_\varepsilon f(x)$  and  $v^* \in \partial_\varepsilon g(y)$  are given we write

$$\begin{aligned} f(x_{m,1}) - f(x) &\geq \frac{1}{m} \langle y - x, u^* \rangle - \varepsilon \\ f(x_{m,i+1}) - f(x_{m,i}) &\geq \frac{1}{m} \langle y - x, u_{m,i}^* \rangle - m^{-1} \gamma_m \varepsilon \quad (i = 1, \dots, m-1) \\ g(x_{m,i-1}) - g(x_{m,i}) &\geq -\frac{1}{m} \langle y - x, v_{m,i}^* \rangle - m^{-1} \gamma_m \varepsilon \quad (i = 1, \dots, m-1) \\ g(x_{m,m-1}) - g(y) &\geq -\frac{1}{m} \langle y - x, v^* \rangle - \varepsilon. \end{aligned}$$

Adding up these inequalities and using the facts that  $x_{m,m} = y$  and  $x_{m,0} = x$ , together with  $u_{m,i}^* = v_{m,i}^* + w_{m,i}^*$ , we obtain that

$$\begin{aligned} f(y) - f(x) + g(x) - g(y) &\geq \frac{1}{m} \langle y - x, u^* - v^* \rangle + \frac{1}{m} \sum_{i=1}^{m-1} \langle y - x, w_{m,i}^* \rangle \\ &\quad - 2(m-1)m^{-1}\gamma_m\varepsilon - 2\varepsilon. \end{aligned}$$

Thus, since  $w_{m,i}^* \in \partial_{m^{-1}\gamma_m\varepsilon} h(\theta)$  we deduce that

$$\begin{aligned} f(y) - f(x) + g(x) - g(y) &\geq \frac{1}{m} \langle y - x, u^* - v^* \rangle - \frac{m-1}{m} h(x-y) \\ &\quad - 2(m-1)m^{-1}\gamma_m\varepsilon - 2\varepsilon \end{aligned}$$

which gives us, as  $m$  goes to  $\infty$  (recall that  $0 < \gamma_m \leq m^{-1}$ ),

$$f(y) - f(x) + g(x) - g(y) \geq -h(x-y) - 2\varepsilon.$$

Hence, by letting  $\varepsilon$  go to 0 we get

$$f(x) - g(x) \leq f(y) - g(y) + h(x-y);$$

that is, (i) follows.  $\blacksquare$

The particular case  $h := 0$  in Theorem 1 yields a new integration result, which relies on the intersection of the  $\varepsilon$ -subdifferentials of the nominal functions. We will denote by  $f_D$  and  $g_D$  the restrictions of  $f$  and  $g$  to  $D$ , respectively.

**Corollary 2** (cf. [2, Corollary 2.5]) *The following statements are equivalent:*

- (i)  *$f$  and  $g$  are convex, lsc on  $D$ , and  $f_D - g_D$  is constant.*
- (ii) *For each  $x \in D$*

$$\emptyset \neq \partial_\varepsilon f(x) \subset \partial_\varepsilon g(x) \quad \text{for all } \varepsilon > 0.$$

- (iii) *For each  $x \in D$  there exists  $\delta > 0$  such that*

$$\emptyset \neq \partial_\varepsilon f(x) \subset \partial_\varepsilon g(x) \quad \text{for all } \varepsilon \in (0, \delta).$$

- (iv) *For each  $x \in D$*

$$\partial_\varepsilon f(x) \cap \partial_\varepsilon g(x) \neq \emptyset \quad \text{for all } \varepsilon > 0.$$

- (v) *For each  $x \in D$  there exists  $\delta > 0$  such that*

$$\partial_\varepsilon f(x) \cap \partial_\varepsilon g(x) \neq \emptyset \quad \text{for all } \varepsilon \in (0, \delta).$$

The following corollary, giving a criterion for integrating the Fenchel subdifferential, is an immediate consequence of Corollary 2 in view of the straightforward relationships  $\partial f(x) \subset \partial_\varepsilon f(x)$  and  $\partial g(x) \subset \partial_\varepsilon g(x)$  for every  $x \in D$  and every  $\varepsilon > 0$ .

**Corollary 3** (cf. [6, Theorem 1]) *The following statements are equivalent:*

(i) *For each  $x \in D$*

$$\emptyset \neq \partial f(x) \subset \partial g(x).$$

(ii) *For each  $x \in D$*

$$\partial f(x) \cap \partial g(x) \neq \emptyset.$$

(iii) *For each  $x \in D$*

$$\emptyset \neq \partial f(x) = \partial g(x).$$

*If these statements hold, then  $f$  and  $g$  are convex, lsc on  $D$ , and  $f_D - g_D$  is constant.*

**Remark 4** a) The preceding results remain true if  $X$  is an arbitrary locally convex real topological vector space, not necessarily Hausdorff. Indeed, the equivalence between the convex and lsc character of a function and the nonemptiness of its  $\varepsilon$ -subdifferentials is a reformulation of the Fenchel-Moreau Theorem, the validity of which in non-Hausdorff spaces has been proved by S. Simons [10, Theorem 10.1].

b) The equivalence between (i) and (ii) in Corollary 2 also follows from a well-known characterization of global minima of DC functions due to J.-B. Hiriart-Urruty [5, Theorem 4.4]. Indeed, according to this characterization, if  $f$  and  $g$  are convex then one has  $\partial_\varepsilon f(x) \subset \partial_\varepsilon g(x)$  for all  $\varepsilon > 0$  if and only if  $x$  is a global minimum of  $f_D - g_D$ . Hence, that condition holds for every  $x \in D$  if and only if every  $x \in D$  is a global minimum of  $f_D - g_D$ , which is obviously equivalent to  $f_D - g_D$  being constant on  $D$ .

From now on we suppose that  $X$  is a normed space with a norm denoted by  $\|\cdot\|$  whose the dual norm is  $\|\cdot\|_*$ . We use  $B_*(\theta, K)$  to denote the closed ball in  $(X^*, \|\cdot\|_*)$  with center  $\theta$  and radius  $K \geq 0$ , and for  $A, B \subset X^*$  we set

$$d(A, B) := \inf \{ \|a - b\|_* : a \in A, b \in B \},$$

with the convention that  $d(A, B) := +\infty$  if  $A$  or  $B$  is empty.

At this moment, we easily get the main result of the paper by taking  $h := K \|\cdot\|$  in Theorem 1:

**Theorem 5** *Let  $K \geq 0$ . Then, the following statements are equivalent:*

(i)  *$f$  and  $g$  are convex, lsc on  $D$ , and  $f_D - g_D$  is Lipschitz with constant  $K$ .*

(ii) *For each  $x \in D$*

$$\emptyset \neq \partial_\varepsilon f(x) \subset \partial_\varepsilon g(x) + B_*(\theta, K) \quad \text{for all } \varepsilon > 0.$$

(iii) *For each  $x \in D$  there exists  $\delta > 0$  such that*

$$\emptyset \neq \partial_\varepsilon f(x) \subset \partial_\varepsilon g(x) + B_*(\theta, K) \quad \text{for all } \varepsilon \in (0, \delta).$$

(iv) For each  $x \in D$

$$\partial_\varepsilon f(x) \cap [\partial_\varepsilon g(x) + B_*(\theta, K)] \neq \emptyset \quad \text{for all } \varepsilon > 0.$$

(v) For each  $x \in D$  there exists  $\delta > 0$  such that

$$\partial_\varepsilon f(x) \cap [\partial_\varepsilon g(x) + B_*(\theta, K)] \neq \emptyset \quad \text{for all } \varepsilon \in (0, \delta).$$

(vi) For each  $x \in D$

$$d(\partial_\varepsilon f(x), \partial_\varepsilon g(x)) \leq K \quad \text{for all } \varepsilon > 0.$$

(vii) For each  $x \in D$  there exists  $\delta > 0$  such that

$$d(\partial_\varepsilon f(x), \partial_\varepsilon g(x)) \leq K \quad \text{for all } \varepsilon \in (0, \delta).$$

**Proof.** The proofs of the equivalences (i)  $\iff$  (ii)  $\iff$  (iii)  $\iff$  (iv)  $\iff$  (v) follow from Theorem 1 by observing that  $\partial_\varepsilon(K \|\cdot\|)(\theta) = B_*(\theta, K)$ . The implications (iv)  $\implies$  (vi)  $\implies$  (vii) are obvious. To prove (vii)  $\implies$  (i), given  $x \in D$  we notice that (vii) implies the existence of  $\delta > 0$  such that, for all  $\gamma > 0$ ,

$$\partial_\varepsilon f(x) \cap [\partial_\varepsilon g(x) + B_*(\theta, K + \gamma)] \neq \emptyset \quad \text{for all } \varepsilon \in (0, \delta).$$

Hence, by the equivalence between (v) and (i),  $f$  and  $g$  are convex, lsc on  $D$ , and  $f_D - g_D$  is Lipschitz with constant  $K + \gamma$ . Therefore, since  $\gamma$  is arbitrary,  $f_D - g_D$  is Lipschitz with constant  $K$ . ■

Observing that statements (i), (iv), (v), (vi) and (vii) in Theorem 5 are symmetric in  $f$  and  $g$ , it turns out that, under the assumptions of this theorem, statements (ii) and (iii) are also symmetric; therefore, if one has

$$\emptyset \neq \partial_\varepsilon f(x) \subset \partial_\varepsilon g(x) + B^*(\theta, K) \quad \text{for all } \varepsilon > 0$$

for each  $x \in D$ , then one also has

$$\emptyset \neq \partial_\varepsilon g(x) \subset \partial_\varepsilon f(x) + B^*(\theta, K) \quad \text{for all } \varepsilon > 0$$

for each  $x \in D$ . We thus obtain the following corollary:

**Corollary 6** *Let  $K \geq 0$ . If some (hence all) of the statements (i)–(vii) of Theorem 5 holds, then for every  $x \in D$  and every  $\varepsilon > 0$  the Hausdorff distance between  $\partial_\varepsilon f(x)$  and  $\partial_\varepsilon g(x)$  does not exceed the constant  $K$ .*

**Corollary 7** *The following statements are equivalent:*

- (i)  $f$  and  $g$  are convex, lsc on  $D$ , and  $f_D - g_D$  is constant.
- (ii) For each  $x \in D$

$$d(\partial_\varepsilon f(x), \partial_\varepsilon g(x)) = 0 \quad \text{for all } \varepsilon > 0.$$

- (iii) For each  $x \in D$  there exists  $\delta > 0$  such that

$$d(\partial_\varepsilon f(x), \partial_\varepsilon g(x)) = 0 \quad \text{for all } \varepsilon \in (0, \delta).$$

From the previous result we obtain a complement to Corollary 3:

**Corollary 8** *The following statements are equivalent:*

(i) *For each  $x \in D$*

$$\emptyset \neq \partial f(x) = \partial g(x).$$

(ii) *For each  $x \in D$*

$$d(\partial f(x), \partial g(x)) = 0.$$

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